



# The non-linear MHD Code JOREK

IPP Ringberg Theory Meeting 2010

**Matthias Hölzl**

① The JOREK Code

② Ongoing Activities

③ Summary

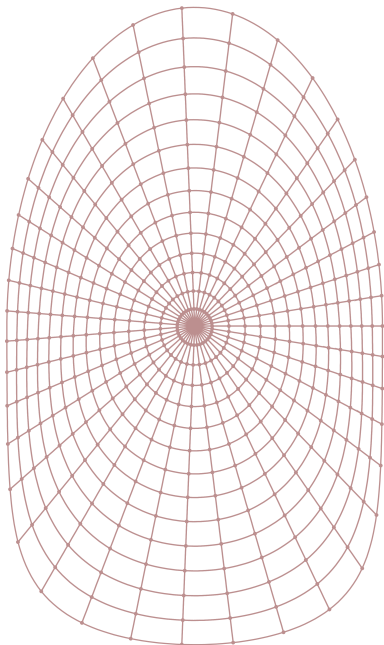
① The JOREK Code

② Ongoing Activities

③ Summary

- 3D non-linear MHD code (divertor tokamaks)
- Developed by Guido Huysmans at CEA Cadarache
- Main target: ELM simulations
- 2D Bezier finite elements
- Toroidal Fourier-decomposition
- Fully implicit time-stepping
- Currently reduced MHD
- MPI + OpenMP (ELM simulation:  $\geq 256$  CPUs)

[G Huysmans et al, Plasma Phys Control Fusion 51, 124012 (2009)]

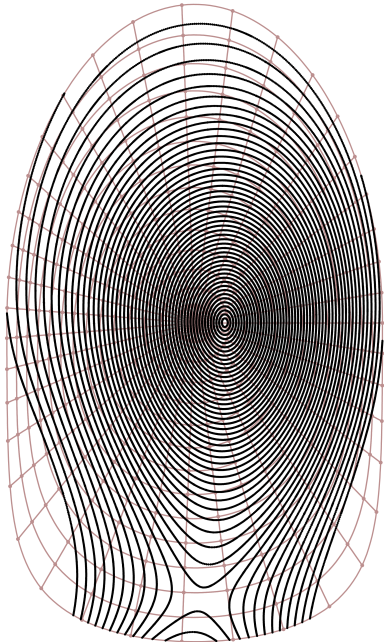


## Typical code run

- Initial grid
- Grad-Shafranov equation

$$\Delta^* \Psi = -\mu_0 R^2 p'(\Psi) - \mu_0^2 f(\Psi) f'(\Psi)$$

- toroidal field
  - pressure profile
  - plasma current profile
  - poloidal flux at boundary
- Flux-surface grid
  - Grad-Shafranov equation
  - Equilibrium refinement
  - Time-integration

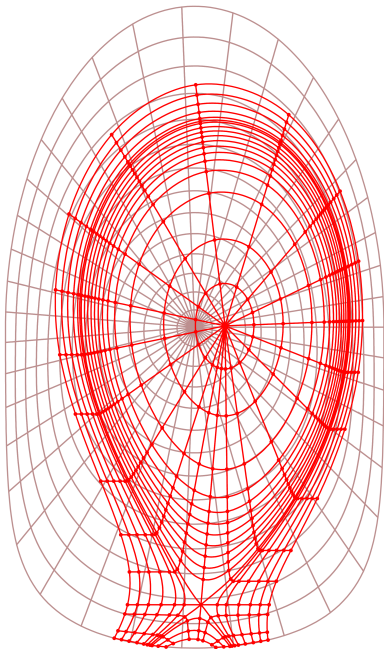


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# Reduced MHD Equations

$$\mathbf{B} = \frac{F_0}{R} \mathbf{e}_\phi + \frac{1}{R} \nabla \Psi \times \mathbf{e}_\phi \quad \mathbf{j} = \Delta^* \Psi$$

$$\mathbf{v} = -R \nabla u \times \mathbf{e}_\phi + v_{||} \mathbf{B} \quad \omega = \nabla_{\text{pol}}^2 u \quad p = \rho T$$

$$\frac{1}{R^2} \frac{\partial \Psi}{\partial t} = \eta(T) \nabla \cdot \left( \frac{1}{R^2} \nabla_\perp \Psi \right) - \frac{1}{R} [\mathbf{u}, \Psi] - \frac{F_0}{R^2} \frac{\partial u}{\partial \phi}$$

$$\mathbf{e}_\phi \cdot \nabla \times \left[ \rho \frac{\partial \mathbf{v}}{\partial t} \right] = \mathbf{e}_\phi \cdot \nabla \times [-\rho(\mathbf{v} \cdot \nabla) \mathbf{v} - \nabla(\rho T) + \mathbf{J} \times \mathbf{B} + \mu \Delta \mathbf{v}]$$

$$\frac{\partial \rho}{\partial t} = -\nabla \cdot (\rho \mathbf{v}) + \nabla \cdot (D_\perp \nabla_\perp \rho) + S_\rho$$

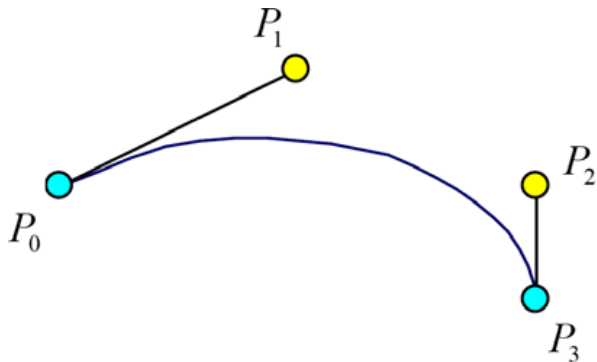
$$\rho \frac{\partial T}{\partial t} = -\rho \mathbf{v} \cdot \nabla T - (\gamma - 1) \rho T \nabla \cdot \mathbf{v} + \nabla \cdot (K_\perp \nabla_\perp T + K_{||} \nabla_{||} T) + S_T$$

$$\mathbf{B} \cdot \left[ \rho \frac{\partial \mathbf{v}}{\partial t} \right] = \mathbf{B} \cdot [-\rho(\mathbf{v} \cdot \nabla) \mathbf{v} - \nabla(\rho T) + \mathbf{J} \times \mathbf{B} + \mu(T) \Delta \mathbf{v}]$$

- $\mathcal{O}(\epsilon^2)$  equations, where  $\epsilon = \alpha/R_0$ ; different models
- The variables  $\Psi$ ,  $u$ ,  $\rho$ ,  $T$ , and  $v_{||}$  are time-integrated (plus  $\mathbf{j}$ - and  $\omega$ -equations)

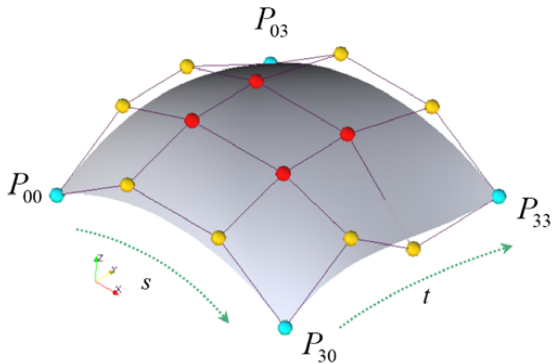


# Bezier Elements



[O Czarny and G Huysmans, J Comput Phys 227, 7423 (2008)]

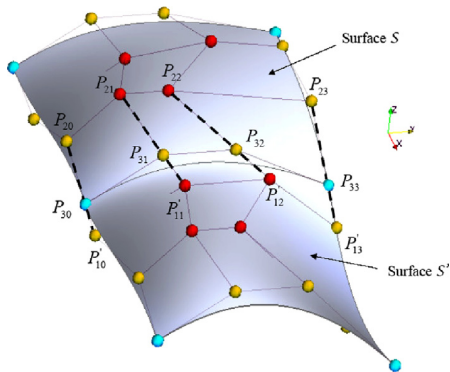
# Bezier Elements



- 2D Bezier finite elements
- Isoparametric

[O Czarny and G Huysmans, J Comput Phys 227, 7423 (2008)]

# Bezier Elements



- 2D Bezier finite elements
- Isoparametric
- $C^1$  continuity  $\Rightarrow$  Four degrees of freedom per node and variable

[O Czarny and G Huysmans, J Comput Phys 227, 7423 (2008)]

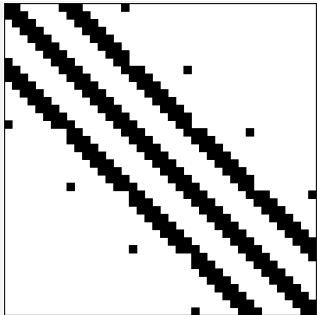
- Linearized Crank-Nicholson

[R M Beam and R F Warming, SIAM Journal on Scientific and Statistical Computing 1, 131 (1980)] [C Hirsch (1991), ISBN 9780471923855]

$$\frac{\partial \mathbf{A}(\mathbf{u})}{\partial t} = \mathbf{B}(\mathbf{u}, t) \rightarrow \left[ \left( \frac{\partial \mathbf{A}}{\partial \mathbf{u}} \right)^n - \frac{\Delta t}{2} \left( \frac{\partial \mathbf{B}}{\partial \mathbf{u}} \right)^n \right] \delta \mathbf{u}^n = \Delta t \mathbf{B}^n$$

$$\delta \mathbf{u}^n = \mathbf{u}^{n+1} - \mathbf{u}^n$$

- Fully implicitly (all equations solved simultaneously)



- Sparse matrix system
- Dense blocks
- Block size:  $n_{\text{tor}} \times n_{\text{var}} \times n_{\text{dof}}$

(Example: low resolution, no X-point)

# Time Stepping

- Linearized Crank-Nicholson

[R M Beam and R F Warming, SIAM Journal on Scientific and Statistical Computing 1, 131 (1980)] [C Hirsch (1991), ISBN 9780471923855]

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$$\delta \mathbf{u}^n = \mathbf{u}^{n+1} - \mathbf{u}^n$$

- Fully implicitly (all equations solved simultaneously)

- PASTIX (Parallel Sparse Matrix Package; direct)

[Hénon et al, Parallel Comput, 28, 301 (2002), [http://dx.doi.org/10.1016/S0167-8191\(01\)00141-7](http://dx.doi.org/10.1016/S0167-8191(01)00141-7)]

- HIPS (Hierarchical Iterative Parallel Solver; direct+ILU)

[J Gaidamour and P Henon, Proceedings PMAA 2008, <http://www.cerfacs.fr/algor/PastWorkshops/SparseDays2008/Slides/henon.pdf>]

- MURGE (common interface to PASTIX and HIPS)

[<https://gforge.inria.fr/projects/murge>]

- GMRES (Generalized Minimal Residual Method; iterative)  
with PASTIX preconditioner (independent solution for toroidal harmonic)

[V. Frayss et al, Technical Report TR/PA/06/09, CERFACS, Toulouse, France, [http://www.cerfacs.fr/algor/reports/2006/TR\\_PA\\_06\\_09.pdf](http://www.cerfacs.fr/algor/reports/2006/TR_PA_06_09.pdf)]

# Discretization of physical equations

- Time integration (implemented more generally)

$$\frac{\partial \mathbf{A}(\mathbf{u})}{\partial t} = \mathbf{B}(\mathbf{u}, t) \rightarrow \left[ \left( \frac{\partial \mathbf{A}}{\partial \mathbf{u}} \right)^n - \frac{\Delta t}{2} \left( \frac{\partial \mathbf{B}}{\partial \mathbf{u}} \right)^n \right] \delta \mathbf{u}^n = \Delta t \mathbf{B}^n$$

- Weak formulation, Partial integration

$$\int_V dV \mathbf{v} (\dots)$$

- Integration by Gauss Quadrature

$$\int_0^1 ds A(s) = \sum_{\mu=1}^4 w_{\mu} A(s_{\mu}) \quad (w_{\mu} \text{ and } s_{\mu}: \text{weights and positions})$$

- Discretization of operators, e.g.,

$$[\mathbf{a}, \mathbf{b}] = \mathbf{a}_{,R} \mathbf{b}_{,Z} - \mathbf{a}_{,Z} \mathbf{b}_{,R} \quad \text{with} \quad \mathbf{a}_{,R} = (\mathbf{a}_{,s} Z_{,t} - \mathbf{a}_{,t} Z_{,s}) / (R_{,s} Z_{,t} - R_{,t} Z_{,s})$$

- Expansion of variables in node degrees of freedom

① The JOREK Code

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③ Summary

# Activities in TOK

- Run the code

RZG, M. Hölzl, W.-C. Müller

- Understand the code

M. Hölzl, W.-C. Müller

- Write a documentation

M. Hölzl

- Improve diagnostics

M. Hölzl

- AUG equilibria

M. Hölzl, E. Strumberger

- Sheared rotation

M. Hölzl, W.-C. Müller

- Free boundary

P. Merkel, G. Huysmans, M. Hölzl

- Tearing modes

M. Hölzl, I. Krebs, W.-C. Müller

- To be done:  
ELMs, Vertical Stability, ...



# Documentation

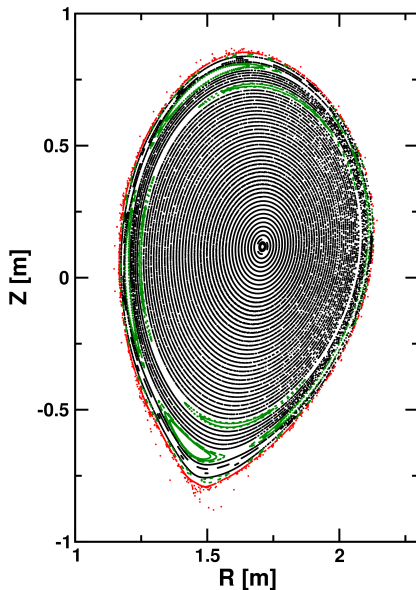
- Currently no real documentation
- Writing down important information successively, e.g.,
  - Coordinate systems and discretization
  - Compiling and running the code
  - Code structure
  - Implementing equations in JOREK
  - Physical equations
  - Time integration
- Currently 50 pages, available on the subversion server

# Diagnostics

- Poincaré plots
- Connection length
- Visualization with VISIT/Paraview (.vtk files)

## New

- Poincaré plots vs.  $\Psi_n - \theta$
- Determination of  $\theta_{\text{mag}}$  (to be improved)
- 2D Fourier analysis using FFTW
- Parallel batch conversions
- Structured HTML job report

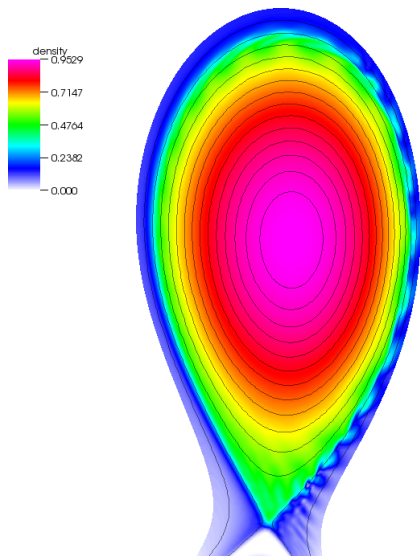


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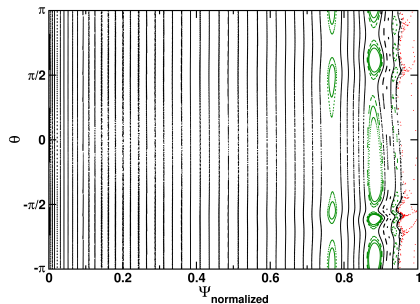


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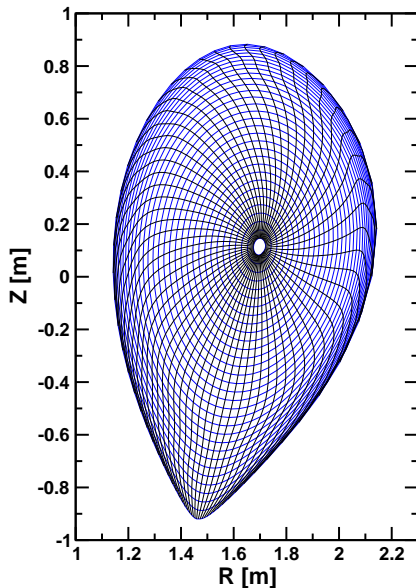


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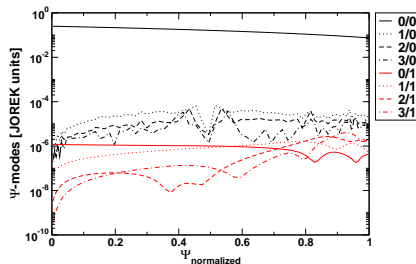


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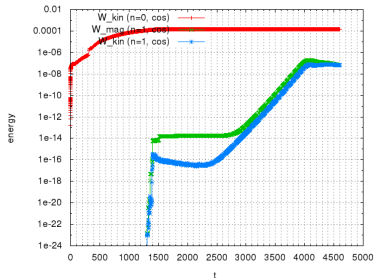
[+] ERRORS AND WARNINGS

[+] README FILES

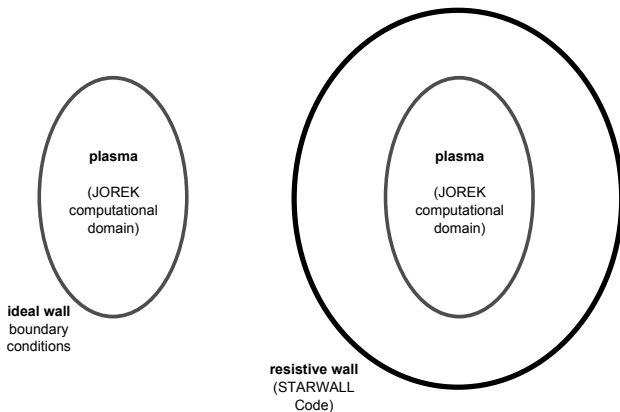
[+] readme

restart of runlb\_noinit\_source at step 390 with u-source increased by factor 5

[+] ENERGY DIAGNOSTIC



# Resistive Walls: Status and Plans



## Physics aims

- Resistive Wall Modes
- Vertical Instabilities
- Disruptions



## Changes in JOREK

- Equilibrium determination
- Time-evolution of wall current potentials,  $Y$ :

$$\dot{Y} = -\frac{1}{\sigma d} \underbrace{D^{-1}} Y - \underbrace{D^{-1} S^T \tilde{M}_{we}} \dot{\Psi}$$

- Boundary integral  $\int dA \nu (\mathbf{B} \times \mathbf{n}) \cdot \mathbf{e}_\phi$  in current equation  $j = \Delta^* \Psi$  (from partial integration)

$$(\mathbf{B} \times \mathbf{n}) \cdot \mathbf{e}_\phi = \underbrace{\tilde{M}_{||,w}} S Y + \underbrace{\tilde{M}_{||,e}} \dot{\Psi} + \underbrace{C}$$

- Matrices computed by STARWALL

Involved: Guido Huysmans, Peter Merkel, Matthias Hölzl

## Status

- Free-boundary equilibrium implemented
  - Some numerical details to be solved
- Boundary integral in current equation
  - $n = 1$  ideal wall response successfully benchmarked with CASTOR
  - $n = 1$  resistive wall response almost finished

## To be done

- Special cases for X-point grid (corners)
- Coupling of harmonics (3D wall)
- Call STARWALL directly from JOREK
- Clean up implementation

# Simulations

## Aim

- Realistic ASDEX Upgrade simulations (ELMs, tearing modes, ...)
- CLISTE equilibria, but pressure profile, e.g., from AUGPED

## Equilibria

- VMEC/NEMEC (semi-automatically)
- Numerical representation of  $ff'$ -profiles
- Works essentially, still some deviations

## Plasma rotation

- Weak rotation  $\Rightarrow$  Strong mode coupling
- Implemented poloidal plasma rotation
  - Initial condition
  - Source term

① The JOREK Code

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## JOREK

- Physical model (reduced MHD)
- Spatial discretization (Bezier elements)
- Time integration scheme (fully implicit)
- Sparse matrix solvers (iterative with physics-based preconditioner)

## Ongoing Activities

- Documentation
- Diagnostics
- Free boundary (RWMs, vertical stability, disruptions)
- AUG equilibria (tearing modes, ELMs)
- Poloidal rotation

# Thanks for your attention!

## Acknowledgements

Guido Huysmans

Wolf-Christian Müller

Sibylle Günter

Peter Merkel

Erika Strumberger

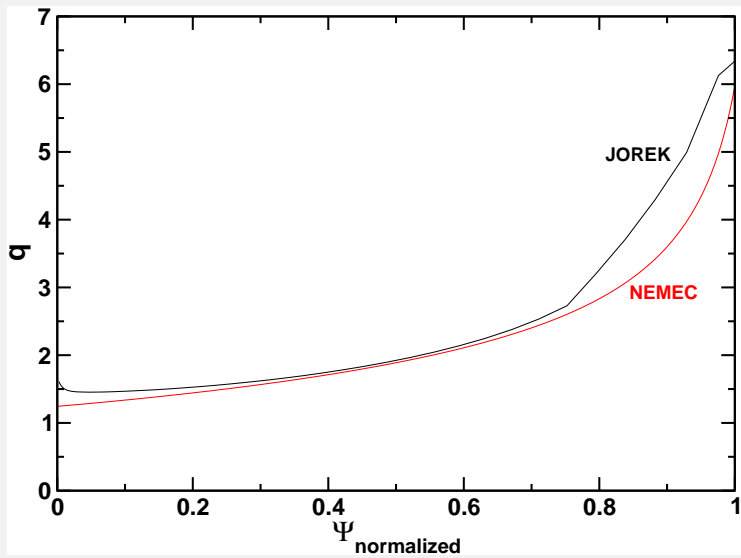
Isabel Krebs

## Selected References

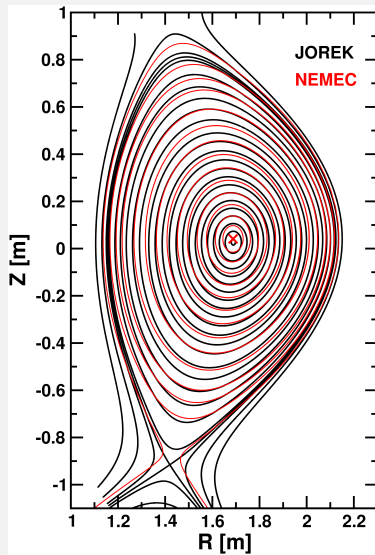
O Czarny and G Huysmans, J Comput Phys 227, 7423 (2008)

G Huysmans et al, Plasma Phys Control Fusion 51, 124012 (2009)

# NEMEC interface



# NEMEC interface





$$\mathbf{B} = \frac{F_0}{R} \mathbf{e}_\phi + \frac{1}{R} \nabla \Psi \times \mathbf{e}_\phi$$

- Field parallel to the interface:

$$\begin{aligned} [\mathbf{B} \times \mathbf{n}] \cdot \mathbf{e}_\phi &= \left[ \left( \frac{F_0}{R} \mathbf{e}_\phi + \frac{1}{R} \nabla \Psi \times \mathbf{e}_\phi \right) \times \mathbf{n} \right] \cdot \mathbf{e}_\phi \\ &= \left[ \mathbf{e}_\phi \left( \mathbf{n} \cdot \frac{1}{R} \nabla \Psi \right) - \frac{1}{R} \nabla \Psi (\mathbf{n} \cdot \mathbf{e}_\phi) \right] \cdot \mathbf{e}_\phi \\ &= \frac{1}{R} \nabla \Psi \cdot \mathbf{n} \end{aligned}$$

- Field perpendicular to the interface:

$$\begin{aligned} \mathbf{B} \cdot \mathbf{n} &= \left[ \frac{F_0}{R} \mathbf{e}_\phi + \frac{1}{R} \nabla \Psi \times \mathbf{e}_\phi \right] \cdot \mathbf{n} \\ &= -\frac{1}{R} (\nabla \Psi \times \mathbf{n}) \cdot \mathbf{e}_\phi \end{aligned}$$

# Who's working on/with JOREK currently?

Stanislas Pamela	Stanislas.Pamela@jet.uk	JET, ELMS
Pierre Ramet	ramet@labri.fr	Pastix
Xavier Lacoste	lacoste@labri.fr	PastiX, Murge, Makefile
Florent Sourbier	florent.sourbier@cea.fr	HPCFF support team
Marina Becoulet	Marina.becoulet@cea.fr	neoclassical flow, RMP
Virginie Grandgirard	Virginie.GRANDGIRARD@cea.fr	numerics
Guillaume Latu	guillaume.latu@cea.fr	parallelisation
Boniface Nkonga	Boniface.Nkonga@unice.fr	full MHD, code platform
Herve Guillard	Herve.Guillard@sophia.inria.fr	turbulence
Matthias Hoelzl	mhoelzl@ipp.mpg.de	vacuum, ELMS, tearing modes
Egbert Westerhof	E.Westerhof@rijnhuizen.nl	tearing modes, ECRH, FP
Ian Chapman	ian.chapman@ccfe.ac.uk	resistive wall modes
Guido Huysmans	guido.huysmans@cea.fr	pellets, numerics, vacuum

Guido Huysmans, 09/2010